

# AL802

## MagnetoResistive FixPitch Sensor

The AL802 is an Anisotropic MagnetoResistive (AMR) position sensor. The sensor contains two Wheatstone bridges shifted against each other. The output signals are proportional to sine and cosine of the coordinate to be measured.

The MR strips of this FixPitch sensor geometrically match to a polepair length of 0.5 mm (equal to a magnetic period of 0.5 mm).

The resistances in this FixPitch sensor are distributed in a PurePitch design (4 poles), thus the errors in the measurement scale are reduced without any signal delay.

It is necessary to oporate the sensor with a stabilizing field (bias field).



Article Description	Package	Delivery Type
AL802ACA-AC	Bare die	Waffle pack (200 pcs.)
AL802ACA-AB	Die on wafer 1)	Waferbox

<sup>1)</sup> Minimum order quantities apply.

#### **Quick Reference Guide**

Symbol	Parameter	Min.	Тур.	Max.	Unit
Р	Pitch (per magnetic pole pair)	-	0.5	-	mm
V <sub>cc</sub>	Supply voltage	-	5.0	-	V
$V_{\rm off}$	Offset voltage per VCC	-0.1	-	+0.1	mV/V
S	Sensitivity 2)	3.0	3.5	4.0	mV/V / kA/m
R <sub>B</sub>	Bridge resistance	5.0	5.6	6.4	kΩ

<sup>&</sup>lt;sup>2)</sup> Periodical differential field with a periodicity of 0.5 mm.

#### **Absolute Maximum Ratings**

Symbol	Parameter	Min.	Max.	Unit
V <sub>CC</sub>	Supply voltage	-9	+9	V
T <sub>amb</sub>	Ambient temperature	-40	+125	°C
T <sub>stg</sub>	Storage temperature	-65	+150	°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.



#### **Features**

- Based on the Anisotropic
   MagnetoResistive (AMR) effect
- Contains two Wheatstone bridges on chip
- PurePitch design (4 poles)
- Ambient temperature range from -40 °C to +125 °C

## **Advantages**

- Contactless angle and position measurement
- Insensitive to interference field
- Minimized offset voltage
- Negligible hysteresis
- Works with active or passive scales

## **Applications**

Incremental or absolute encoder for linear or rotary movements in various industrial applications.







## **Magnetical Data**

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
H <sub>x</sub>	Stabilizing magnetic field		-	3.0	-	kA/m

## **Electrical Data**

 $T_{amb} = 25$  °C;  $H_{x} = 3$  kA/m;  $V_{CC} = 5$  V; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V <sub>CC</sub>	Supply voltage		-	5.0	-	V
V <sub>off</sub>	Offset voltage per VCC		-0.1	-	+0.1	mV/V
TC <sub>Voff</sub>	Temperature coefficient of Voff *		-3.0	-	+3.0	(μV/V)/K
R <sub>B</sub>	Bridge resistance 2)		5.0	5.6	6.4	kΩ
TC <sub>RB</sub>	Temperature coefficient of RB <sup>3)</sup>		0.24	0.28	0.32	%/K
S	Sensitivity 4)		3.0	3.5	4.0	mV/V / kA/m
TCs	Temperature coefficient of sensitivity 5)		-0.48	-0.42	-0.36	%/K
V <sub>off D</sub>	Offset drift over time	T <sub>amb</sub> = 85 °C	-100	-	+100	μV/V

$$^{1)} \quad TC_{Voff} = \frac{V_{off(T2)} - V_{off(T1)}}{T_2 - T_1} \quad with \ T_1 = +25 \ ^{\circ}C; \ T_2 = +125 \ ^{\circ}C.$$

<sup>2)</sup> Bridge resistance between pads 1 and 6, 2 and 5.

3) 
$$TC_{BB} = 100 \cdot \frac{R_{B(T2)} - R_{B(T1)}}{R_{B(T1)} \cdot (T_2 - T_1)}$$
 with  $T_1 = +25 \, ^{\circ}C$ ;  $T_2 = +125 \, ^{\circ}C$ .

<sup>4)</sup> Periodical differential field with a periodicity of 0.5 mm.

$$^{5)} \quad TC_{S} = 100 \quad \frac{S_{(T2)} - S_{(T1)}}{S_{(T1)} \cdot (T_{2} - T_{1})} \quad \text{with } T_{1} = +25 \, ^{\circ}\text{C}; \ T_{2} = +125 \, ^{\circ}\text{C}.$$

AL802
MagnetoResistive Length Sensor

## **Dynamical Data**

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
f	Frequency range		1.0 1)	-	-	MHz

<sup>&</sup>lt;sup>1)</sup> No significant amplitude attenuation.

## **General Data**

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Р	Pitch (per magnetic pole pair)		-	0.5	-	mm
d	Distance 2)		-	0.25	-	mm
T <sub>amb</sub>	Ambient temperature		-40	-	+125	°C
T <sub>stg</sub>	Storage temperature		-65	-	+150	°C

 $<sup>^{\</sup>mbox{\tiny 2)}}$  Typical working distance, depends on the magnetic field strength of the scale.



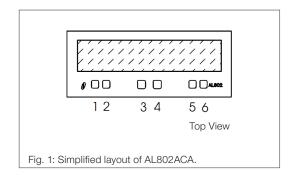
## **Pinning**

Pad	Symbol	Parameter
1	+V <sub>O2</sub>	Positive output voltage bridge 2
2	+V <sub>01</sub>	Positive output voltage bridge 1
3	V <sub>cc</sub>	Supply voltage
4	GND	Ground
5	-V <sub>01</sub>	Negative output voltage bridge 1
6	-V <sub>O2</sub>	Negative output voltage bridge 2

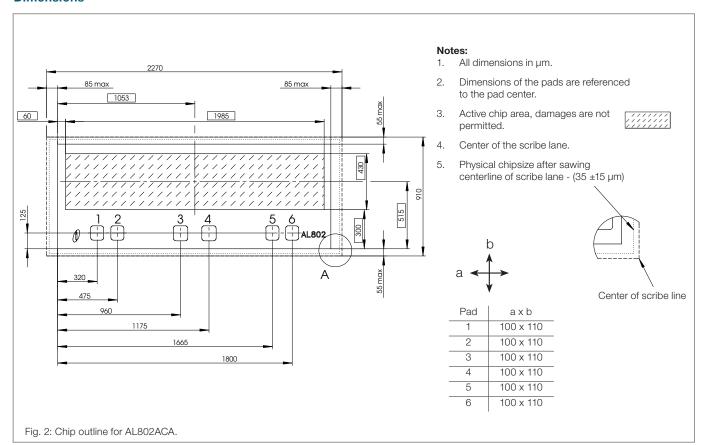
Polarity of bridge outputs is defined as follows:

 $V_{O1} = (+V_{O1}) - (-V_{O1})$ 

 $V_{O2} = (+V_{O2}) - (-V_{O2})$ 



## **Dimensions**



## **Data for Packaging and Interconnection Technologies**

Parameter	Value	Unit
Chip area <sup>1)</sup>	2.27 x 0.91	mm <sup>2</sup>
Chip thickness	525 ± 10	μm
Pad size	See Fig. 2	-
Pad thickness	0.8	μm
Pad material	AlCu	-

<sup>1)</sup> Tolerances of he chip size see fig. 2

## **General Information**

#### **Product Status**

Article	Status
AL802ACA-AC	The product is in series production.
AL802ACA-AB	The product is in series production.
Note	The status of the product may have changed since this data sheet was published. The latest information is available on the internet at www.sensitec.com.

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## Changelist

Version	Description of the Change	Date
AL802.DSE.04	Disclaimer supplement	06/2022
AL802.DSE.03	Change of corporate design (pp. 1-6)	01/2022
AL802.DSE.00	Original (pp. 1-6)	11/2012

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