

# GF705

## MagnetoResistive Magnetic Field Sensor

The GF705 is a magnetic fi eld sensor based on the multilayer Giant MagnetoResistive (GMR) effect. The Sensor contains a Wheatstone bridge with on-chip flux concentrators to improve the sensitivity. The sensor is ideal for measuring magnetic fi elds in a linear range from 1.8 mT up to 8 mT.

A typical application is endpoint detection through a cylinder of stainless steel: A moving magnet inside a thick-walled cylinder is detected by a GF705 sensor from the outside.

The GF705 is available as bond version (bare die) and as flip-chip or LGA-package or vertical package for SMD assembly.



### **Product Overview**

Article description	Package	Delivery Type	
GF705ACA-AB 1)	Bare Die	Waferbox	
GF705APA-AB	Flip-Chip	Tape on reel (5000)	
GF705AMA-AE	LGA6S	Tape on reel (2000)	
GF705AMS-AS	SIL4-D	Tape on reel (tbd.)	

<sup>1)</sup> minimum order quantities apply.

#### **Features**

- Based on the GiantMagnetor-Resistive (GMR) effect
- Flip-chip assembly
- Wide temperature range from –40°C up to +125°C

#### **Quick Overview**

Symbol	Parameter	min.	typ.	max.	Unit
V <sub>CC</sub>	Supply voltage	-	5.0	-	V
B <sub>Lin</sub>	Linear magnetic range	1.8	-	8.0	mT
S	Sensitivity (in linear range)	8	10	13	mV/V/ mT
R <sub>B</sub>	Bridge resistance	4.0	5.0	7.0	kΩ

#### **Advantages**

- Large working distance
- Excellent absolute accuracy
- Large range of magnetic field strength
- Very small size
- Contactless field measurement

## **Absolute Maximum Ratings**

The ratings do not imply opening conditions; functional operation is not guaranteed. Beyond these values damage may occur.

Symbol	Parameter	min.	max.	Unit
V <sub>CC</sub>	Supply voltage	-9.0	9.0	V
T <sub>amb</sub>	Ambient temperature	-40	+125	°C

### **Applications**

- End-point detection
- Reference monitoring
- Magnetic switches







## **Magnetic Data**

Symbol	Parameter	Conditions	min.	typ.	max.	Unit
B <sub>LIN</sub>	Linear magnetic flux density range (abs)	See Fig. 1	1.8	-	8.0	mT
B <sub>sat</sub>	Saturation magnetic flux density 1)	See Fig. 1	-	±25.0	-	mT

 $<sup>^{\</sup>scriptscriptstyle{(1)}}$  At  $B_{\scriptscriptstyle{sat}}$  the sensor delivers the maximal output voltage  $V_{\scriptscriptstyle{peak}}$ . By exceeding the value  $B_{\scriptscriptstyle{sat}}$  the output signal is not longer unique.

### **Electrical Data**

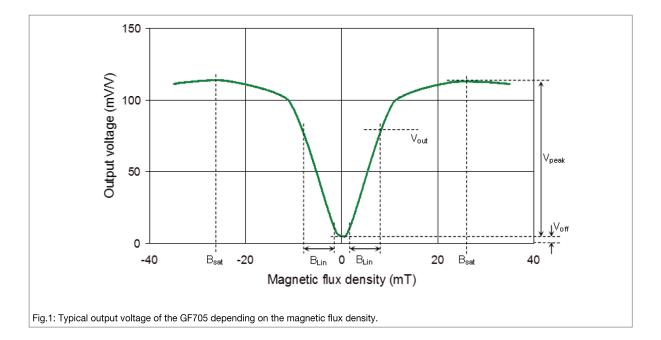
 $T_{amb}$  = +25°C, unless otherwise specified

Symbol	Parameter	Conditions	min.	typ.	max.	Unit
$V_{CC}$	Supply voltage		-	5.0	-	V
S	Sensitivity	B = (1.88) mT	8	10	13	mV/V/ mT
TCs	Temperature coefficient of Sensitivity 2)	T <sub>amb</sub> = (-40+125) °C	-0.26	-0.22	-0.18	%/K
R <sub>B</sub>	Bridge resistance 3)		4.0	5.0	7.0	kΩ
TC <sub>RB</sub>	Temperature coefficcient of RB 4)	T <sub>amb</sub> = (-40+125) °C	0.17	0.20	0.23	%/K
V <sub>peak</sub>	Maximum output voltage 5)	See Fig. 1	_	110	-	mV/V
$V_{out}$	Voltage output delta <sup>6)</sup> V <sub>OUT(3 mT)</sub> - V <sub>OUT(0 mT)</sub>	0 mT @90 deg 3 mT @0 deg	12.3	-	27.4	mV/V

$$^{2)} \quad TC_{s}{=} \ 100 \cdot \frac{S_{(72)} \cdot S_{(71)}}{S_{(71)} \cdot (T_{2} - T_{1})} \quad \text{with } T_{1} = 25 \ ^{\circ}C; \ T_{2} = 125 \ ^{\circ}C,$$

<sup>4)</sup> 
$$TC_{RB} = 100 \cdot \frac{R_{B(T2)} \cdot R_{B(T1)}}{R_{B(T)} \cdot (T_2 - T_1)}$$
 with  $T_1 = 25 \,^{\circ}C$ ;  $T_2 = 125 \,^{\circ}C$ .

- 5) Maximal output voltage at B<sub>sat</sub>.
- <sup>6)</sup> Parameter checked on 96 samples.



 $<sup>^{\</sup>mbox{\tiny 3)}}$  Bridge resistance between pads 1 and 3 and 2 and 4.

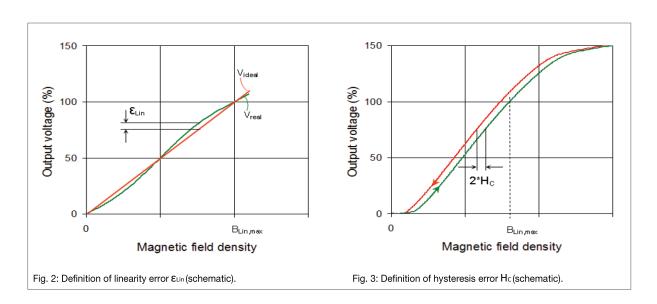


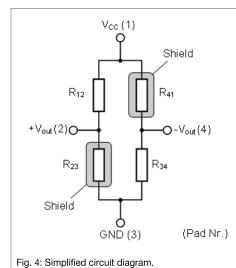
#### **Performance Data**

 $T_{amb} = +25$ °C, unless otherwise specified

Symbol	Parameter	Conditions	min.	typ.	max.	Unit
V <sub>off</sub>	Offset voltage per V <sub>CC</sub>	See Fig. 1	-5.0	-	+5.0	mV/V
TC <sub>Voff</sub>	Temperature coefficient of Voff	T <sub>amb</sub> = (-40+125) °C	-20	7	+25	μV/V/K
<b>E</b> Lin	Linearity error	B = (1.88) mT; see Fig. 2	-	2	5	% of V <sub>out</sub>
H <sub>C</sub>	Hysteresis error 1)	See Fig. 3	-	0.05	0.1	mT

 $<sup>^{1)}</sup>$  The hysteresis error is ascertained in the magnetic field, ramped from 10 mT to -10 mT and back to 10 mT. The value is specified for the linear range  $B_{\text{Lin}}$ .





In Fig. 4 the resistors R23 and R41 are covered by two flux concentrators (shields) to prevent an applied magnetic fi eld from influencing them. Therefore, when a fi eld is applied, the resistors R12 and R34 decrease in resistance, while the other two resistors under the fl ux concentrator do not. This imbalance leads to the bridge output.



### **Bare die and Flip-Chip**

### **Pinning**

Pad	Symbol	Parameter
1	V <sub>CC</sub>	Supply voltage
2	$+V_{out}$	Positive output voltage
3	GND	Ground
4	-V <sub>out</sub>	Negative output voltage

#### Note:

Pin 1 is not marked on the chip. Since the chip is symmetrical, its orientation is only defi ned by its long and short side.

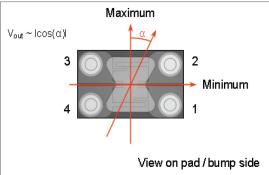
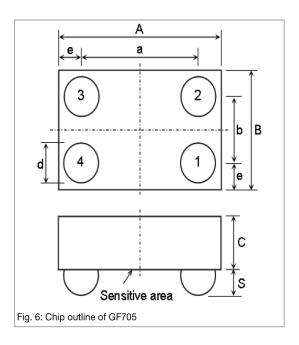


Fig. 5: Top: GF705 on its pad / bump side shown with the direction of its sensitivity. Bottom: Marked side of the flip-chip version only.

### **Mechanical Data**

Symbol	Pai	rameter	min.	typ.	max.	Unit
Α		Length	1435	1460	1485	μm
В	die	Width	935	960	985	μm
С	Bare	Height	240	250	260	μm
d		Diameter	-	230	-	μm
Α		Length	1425	1460	1485	μm
В	ے	Width	935	960	985	μm
С	Flip-chip	Height	400	410	420	μm
d	i≣	Diameter 1)	-	300	-	μm
S		Standoff 2)	-	240	-	μm
а		Pitch a	-	1000	-	μm
b		Pitch b	-	500	-	μm
е		Pitch c	-	230	-	μm

<sup>1)</sup> Diameter of solter balls before reflow



### **Data for Packaging an Interconnection Technologies**

Symbol	Parameter	Conditions	Value	Unit
Bare die	Pad material		Au	-
Daile Gle	Pad thickness		0.4	μm
Flip obin	Solder ball material		SnAg2.6Cu0.6	-
Flip-chip	Maximum solder temperature	For 6 s	260	°C

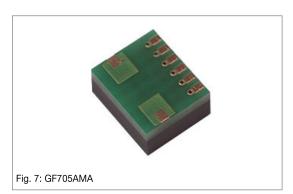
<sup>2)</sup> After reflow



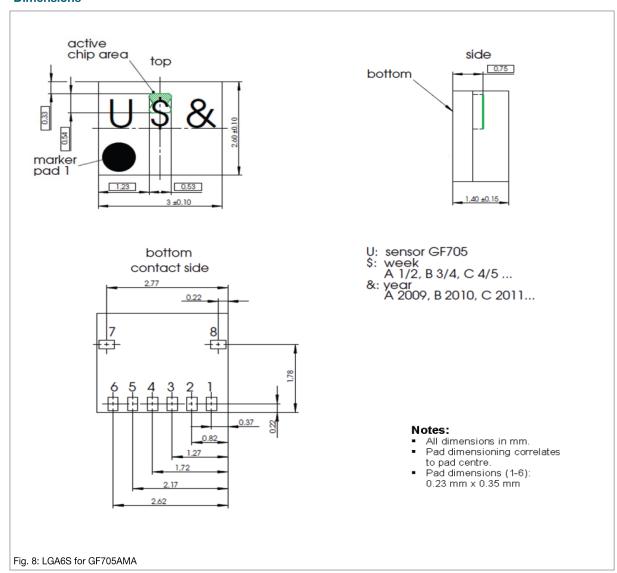
### LGA6S

### **Pinning**

Pad	Symbol	Parameter
1	+V <sub>out</sub>	Positive output voltage
2	NC	Not connected
3	GND	Ground
4	V <sub>CC</sub>	Supply voltage
5	-V <sub>out</sub>	Negative output voltage
6-8	NC	Not connected



### **Dimensions**

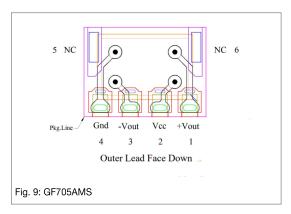




## SIL4-D

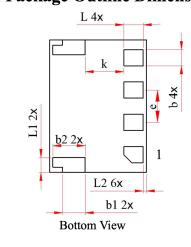
## **Pinning**

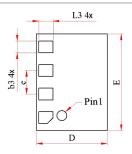
Pad	Symbol	Parameter		
1	+V <sub>out</sub>	Positive output voltage		
2	V <sub>CC</sub>	Supply voltage		
3	-V <sub>out</sub>	Negative output voltage		
4	GND	Ground		
5-6	NC	Not connected		

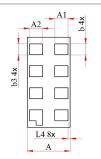


### **Dimensions**









Top View

Side View

Cb1	Dimens	sion In Mill	imeters	Dimension In Inches		
Symbol	Normal	Min	Max	Normal	Min	Max
Α		0.950	1.050		0.037	0.0411
A1		0.220	0.350		0.009	0.014
A2		0.220	0.350		0.009	0.014
D	1.500	1.450	1.550	0.059	0.057	0.061
E	2.050	2.000	2.100	0.081	0.079	0.083
b	0.250	0.200	0.300	0.010	0.008	0.012
b1	0.350	0.300	0.400	0.014	0.012	0.016
b2	0.500	0.450	0.550	0.020	0.018	0.022
b3	0.250	0.200	0.300	0.010	0.008	0.012
L	0.300	0.250	0.350	0.012	0.010	0.014
L1	0.230	0.180	0.280	0.009	0.007	0.011
L2	0.050	0.010	0.090	0.002	0.000	0.004
L3	0.300	0.250	0.350	0.012	0.010	0.014
L4	0.050	0.010	0.090	0.002	0.000	0.004
k	0.600 REF			0.024 REF		
e	0.500 BSC			0.050 BSC		

Fig. 10: SIL4-D for GF705AMS



#### **General Information**

#### **Product Status**

Article	Status	
GF705ACA-AB	The product is in series production.	
GF705APA-AB	The product is in series production.	
GF705AMA-AE	The product is in series production.	
GF705AMS-AS	The product is under development.	
Note	The status of the product may have changed since this data sheet was published. The latest information is available on the internet at www.sensitec.com.	

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#### Changelist

Version	Description of the Change	Date
GF705.DSE.13	Change of article description (p. 1 product overview) Add new product variant (GF705AMS)	05/2023
GF705.DSE.12	Various textual changes	07/2018
GF705.DSE.11	Various textual changes	04/2017
GF705.DSE.10	Change of corporate design (pp. 1-7)	05/2015
GF705.DSE.00	Original (pp. 1-7)	11/2006

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