

AL794

MagnetoResistive FixPitch Sensor (2.5 mm)

The AL794 is an AnisotropicMagnetoResistive (AMR) position sensor with a high resistance for low power applications. The sensor contains two Wheatstone bridges shifted against each other. The output signals are proportional to sine and cosine of the coordinate to be measured.

The MR strips of this FixPitch sensor geometrically match to a pole length of 2.5 mm (equal to a magnetic period of 5 mm). Additionally, the sensor layout incorporates PerfectWave technology, i. e. the position of each block of MR strips has a special arrangement to filter higher harmonics and to increase the signal quality. The resistores in this FixPitch sensor are distributed over several poles (2), thus the errors in the magnetic measurement scale are reduced without any signal delay. The amplitude is almost constant in a wide working range between sensor and magnetic scale. The bond version of AL794 is available as bare die. For SMD processing, the sensor is available in a Sil6 or LGA package.



| Article description | Package | Delivery Type |
|---------------------|--------------|-------------------------|
| AL794ACA-AB 1) | Die on Wafer | Waferbox |
| AL794BCA-AB 1) | Die on Wafer | Waferbox |
| AL794AKA-AC | SIL6 | Waffle pack (90 pcs) |
| AL794AMA-AE | LGA6L | Tape on reel (2000 pcs) |
| AL794BMA-AE | LGA6L | Tape on reel (2000 pcs) |
| AL794 Evalboard | Evalboard | ESD-Box |

¹⁾ minimum order quantities apply.

Quick Reference Guide

| Symbol | Parameter | min. | typ. | max. | Unit |
|-------------------|--------------------------------------|------|------|------|------|
| Р | Pitch (magnetic pole length) | - | 2.5 | - | mm |
| V _{CC} | Supply voltage | - | 5.0 | - | V |
| V _{off} | Offset voltage per V _{CC} | -2.0 | - | +2.0 | mV/V |
| V _{peak} | Signal amplitude per V _{CC} | 9.0 | 11.0 | 13.0 | mV/V |
| R _B | Bridge resistance (Version A) | 52.0 | 62.0 | 72.0 | kΩ |
| R _B | Bridge resistance (Version B) | 71.0 | 84.0 | 97.0 | kΩ |

Absolute Maximum Ratings

In accordance with the absolute maximum rating system (IEC60134).

| Symbol | mbol Parameter | | Max. | Unit |
|--------------------------|------------------------------|------|------|------|
| V _{CC} | Supply voltage | -9.0 | +9.0 | V |
| T _{amb} | Ambient temperature | -40 | +125 | °C |
| T _{stg(Die)} | Storage temperature (Die) | | +150 | °C |
| T _{stg(others)} | Storage temperature (others) | -40 | +125 | °C |

Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device.

This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.





Features

- Based on the AnisotropicMagnetoResistive (AMR) effect
- Contains two high resistance wheatstone bridges on Chip
- Sine and Cosine output
- Adapted to 2.5 mm poles
- PurePitch design (2 poles)
- PerfectWave technology
- Ambient temperature range from -40 °C to +125 °C

Advantages

- Contactless angle and position measurement
- Large air gap
- Excellent accuracy
- Minimized offset voltage
- Negligible hysteresis

Applications

Incremental or absolute encoder for linear or rotary movements in various industrial applications, such as:

- Motor integrated encoder
- Motorfeedback system
- Linear guide





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Magnetic Data

| Symbol | Parameter | Conditions | min. | typ. | max. | Unit |
|------------------|----------------------------|------------|------|------|------|------|
| H _{ext} | Magnetic field strength 1) | | 20.0 | 25.0 | - | kA/m |

 $^{^{1)}}$ The stimulating magnetic field in the sensor plane to ensure minimum error specified in note 8.

Electrical Data

 T_{amb} = +25°C, H_{ext} = 25 kA/m; V_{CC} = 5.0 V; unless otherwise specified.

| Symbol | Parameter | Conditions | min. | typ. | max. | Unit |
|---------------------|---|--------------------------------|-------|-------|-------|----------|
| V _{CC} | Supply voltage | | - | 5.0 | - | V |
| V _{off} | Offset voltage per V _{CC} | See Fig. 2 | -2.0 | - | +2.0 | mV/V |
| TC _{Voff} | Temperature coefficient of V _{off} ²⁾ | T _{amb} = (-40+125)°C | -5.0 | - | +5.0 | (μV/V)/K |
| V_{peak} | Signal amplitude per V _{CC} 3) | See Fig. 2 | 9.0 | 11.0 | 13.0 | mV/V |
| TC _{Vpeak} | Temperature coefficient of V _{peak} 4) | T _{amb} = (-40+125)°C | -0.48 | -0.42 | -0.36 | %/K |
| R _B | Bridge resistance (Version A) 5) | | 52.0 | 62.0 | 72.0 | kΩ |
| R _B | Bridge resistance (Version B) 5) | | 71.0 | 84.0 | 97.0 | kΩ |
| R _s | Sensor resistance (Version A) 6) | | 26.0 | 31.0 | 36.0 | kΩ |
| R _s | Sensor resistance (Version B) 6) | | 35.5 | 42.0 | 48.5 | kΩ |
| TC _{RB} | Temperature coefficient of R _B 7) | T _{amb} = (-40+125)°C | 0.24 | 0.28 | 0.32 | %/K |

 $^{}_{2)}\ TC_{Voff=}100\frac{V_{off(T2)}V_{off(T1)}}{T_{2}\text{-}T_{1}}\ with\ T_{1}=+25^{\circ}C;\ T_{2}=+125^{\circ}C.$

$$^{4)} \ TC_{VPeak}\!\!=\!\!100 \cdot \! \frac{V_{Peak(T2)}\!\!-\!\!V_{Peak(T1)}}{V_{Peak(Tamb)'}(T_2\!\!-\!\!T_1)} \ with \ T_1 = +25^{\circ}C; \ T_2 = +125^{\circ}C.$$

$$\label{eq:TCRB} \ensuremath{\mathcal{T}} \ensuremath{\mathsf{TC}}_{\mathsf{RB}} = 100 \cdot \frac{R_{B(T2)} - R_{B(T1)}}{R_{B(Tamb)} \cdot (T_2 - T_1)} \mbox{ with } T_1 = +25^{\circ}C \ensuremath{\, T}_2 = +125^{\circ}C \ensuremath{\, .}$$

Accuracy

 T_{amb} = +25°C, H_{ext} = 25 kA/m; V_{CC} = 5.0 V; unless otherwise specified.

| Symbol | Parameter | Conditions | min. | typ. | max. | Unit |
|--------|--------------------------|------------|------|------|------|------------------------|
| ΔΧ | Measurement error 8) | | - | 25.0 | 30.0 | μm |
| k | Amplitude synchronism 9) | | - | 0.1 | 1 | % of V _{peak} |

⁸⁾ $\Delta X = |X_{real} - X_{measured}|$ without offset influences due deviations from ideal sinusoidal characteristics (ascertained at an ideal magnetic scale).

Dynamic Data

| Symbol | Parameter | Conditions | min. | typ. | max. | Unit |
|--------|-----------------|------------|---------|------|------|------|
| f | Frequency range | | 1.0 10) | - | - | MHz |

¹⁰⁾ No significant amplitude loss in this frequency range.

General Data

| Symbol | Parameter | Conditions | min. | typ. | max. | Unit |
|------------------|-------------------------------|------------|------|------|------|------|
| Р | Pitch (mangnetic pole length) | See Fig. 1 | - | 2.5 | - | mm |
| d | Distance 11) | | - | 1.0 | - | mm |
| T _{amb} | Ambient temperature | | -40 | - | +125 | °C |

 $^{^{\}scriptsize 11)}$ See Fig. 3 for detailed information.

 $^{^{3)}}$ Maximal output voltage without offset influences. Periodicity of V_{peak} is sin(P) and cos(P).

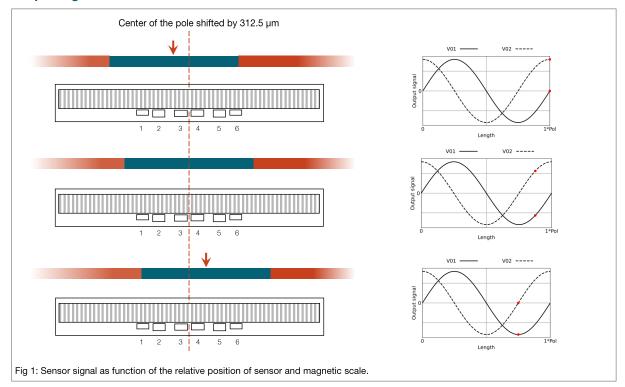
 $^{^{5)}}$ Bridge resistance between +V $_{\rm O1}$ and -V $_{\rm O1}$, +V $_{\rm O2}$ and -V $_{\rm O2}$

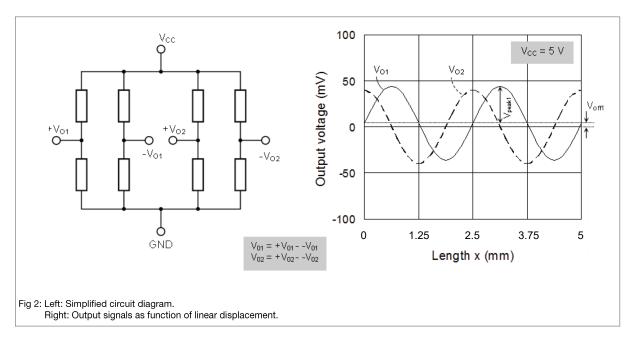
 $^{^{6)}}$ Sensor resistance between V_{CC} and GND.

⁹⁾ k=100-100 $\cdot \frac{V_{Peak1}}{V_{Peak2}}$



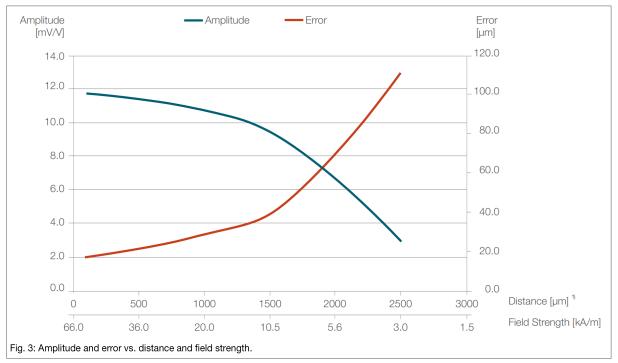
Output Signal Information







Typical Performance Graphs



¹⁾ In use with a plastic bounded hard ferrite magnetic scale (Br = 220 mT, thickness 1 mm, mounted on stainless steel),



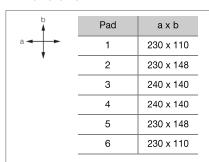
AL794ACA/AL794BCA Bare Die

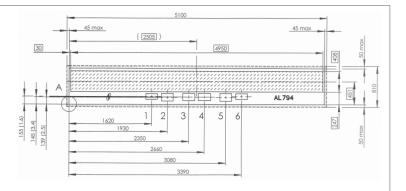
Pinout

| Pad | Symbol | Parameter |
|-----|------------------|----------------------------------|
| 1 | +V _{O1} | Positive output voltage bridge 1 |
| 2 | +V _{O2} | Positive output voltage bridge 2 |
| 3 | V _{cc} | Supply voltage |
| 4 | GND | Ground |
| 5 | -V _{O1} | Negative output voltage bridge 1 |
| 6 | -V ₀₂ | Negative output voltage bridge 2 |



Dimensions





Notes:

- All Dimensions in µm
- Pad dimensioning correlates the dicing line
- The dashed outline represents the dicing line
- The shaded area denotes the active chip area. This must be not touched during handling or assembly since this may cause damage the chip. Using a die collet for handling is recommened.

Fig. 5: Chip outline for AL794xCA as bare die.

Data for Packaging and Interconnection Technologies

| Parameter | Value | Unit |
|----------------|------------|------|
| Chip area 1) | 5.1 x 0.81 | mm² |
| Chip thickness | 525 ± 10 | μm |
| Pad size | See Fig. 5 | - |
| Pad thickness | 0.8 | μm |
| Pad material | AlCu | - |

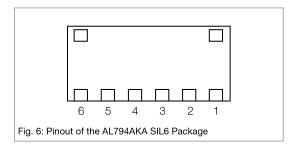
¹⁾ Tolerances of chip see Fig. 5.



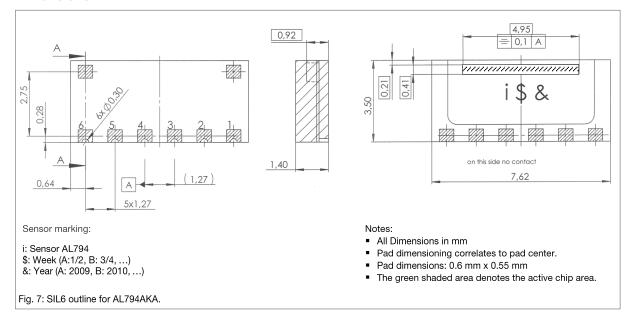
AL794AKA SIL6 Package

Pinout

| Pad | Symbol | Parameter |
|-----|------------------|----------------------------------|
| 1 | +V _{O1} | Positive output voltage bridge 1 |
| 2 | +V _{O2} | Positive output voltage bridge 2 |
| 3 | V _{CC} | Supply voltage |
| 4 | GND | Ground |
| 5 | -V _{O1} | Negative output voltage bridge 1 |
| 6 | -V _{O2} | Negative output voltage bridge 2 |



Dimensions

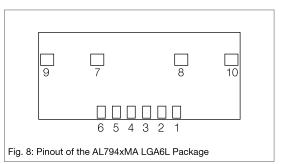




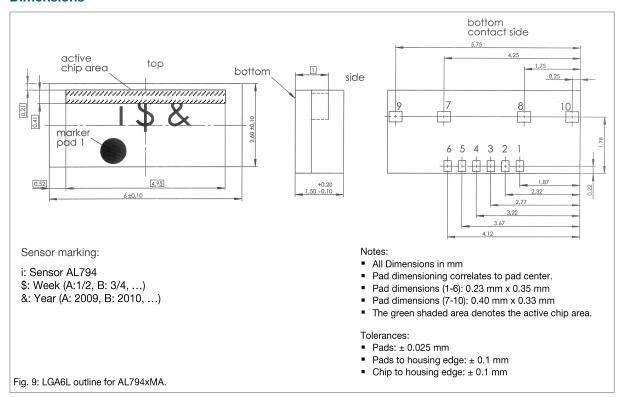
AL794AMA/AL794BMA LGA6L Package

Pinout

| Pad | Symbol | Parameter |
|------|------------------|----------------------------------|
| 1 | +V _{O1} | Positive output voltage bridge 1 |
| 2 | +V _{O2} | Positive output voltage bridge 2 |
| 3 | GND | Ground |
| 4 | V _{CC} | Supply voltage |
| 5 | -V _{O1} | Negative output voltage bridge 1 |
| 6 | -V _{O2} | Negative output voltage bridge 2 |
| 7-10 | NC | Not connected |



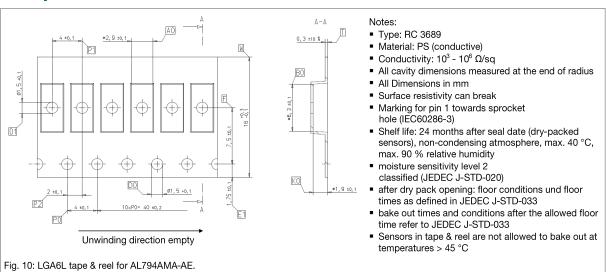
Dimensions



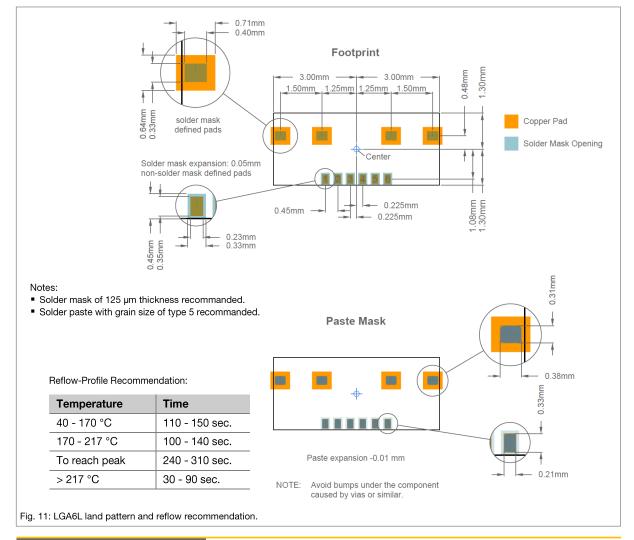


AL794AMA/AL794BMA LGA6L Package

Reel layout



Land pattern layout

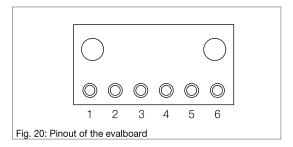




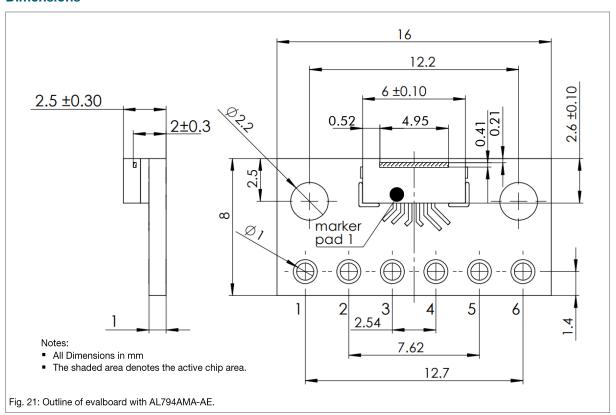
Evalboard with AL794AMA-AE

Pinout

| Pad | Symbol | Parameter |
|-----|------------------|----------------------------------|
| 1 | +V _{O1} | Positive output voltage bridge 1 |
| 2 | +V _{O2} | Positive output voltage bridge 2 |
| 3 | GND | Ground |
| 4 | V _{CC} | Supply voltage |
| 5 | -V _{O1} | Negative output voltage bridge 1 |
| 6 | -V _{O2} | Negative output voltage bridge 2 |

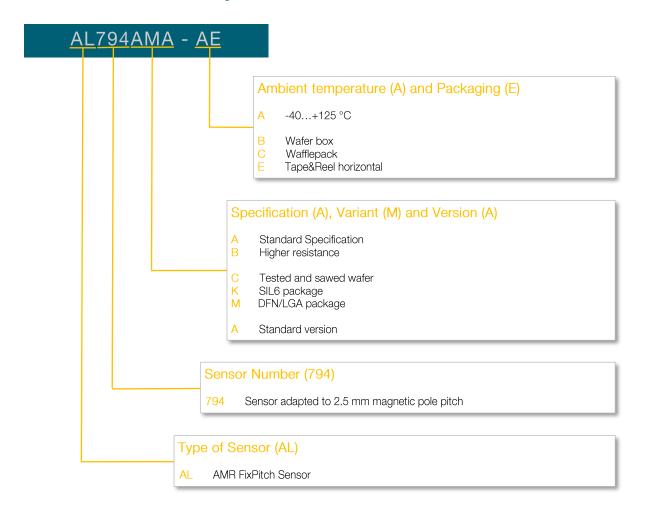


Dimensions





Additional Information on Ordering Code



Special Design Features



Sensors with PerfectWave design provide the best signal quality, highest accuracy and optimal sensor linearity by filtering out higher harmonics in the signal. The linearity of the sensor is assured, even for weak magnetic field measurment.



In PurePitch sensors, the FixPitch principle is extended over several poles in order to increase accuracy still further. This arrangement reduces the influence of errors in the measurment scale and improves the immunity to interference fields.



FixPitch sensors are adapted to the pole length (pitch) of the measurment scale. The linearity of the sensor is optimized and the influence of interference fields is minimized.



General Information

Product Status

| Article | Status | |
|-----------------|--|--|
| AL794ACA-AB | The product is in series production. | |
| AL794BCA-AB | The product is in series production. | |
| AL794AKA-AC | The product is in series production. | |
| AL794AMA-AE | The product is in series production. | |
| AL794BMA-AE | The product is in series production. | |
| AL794 Evalboard | This product is for evaluation of the AL794AMA-AE sensor. | |
| Note | The status of the product may have changed since this data sheet was published. The latest information is available on the internet at www.sensitec.com. | |

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Application Information

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Changelist

| Version | Description of the Change | Date |
|--------------|---|---------|
| AL794.DSE.10 | Add evalboard information (p. 9) | 12/2024 |
| AL794.DSE.09 | Disclaimer supplement | 06/2022 |
| AL794.DSE.08 | Change of technical data (p. 1, 2, 5, 7, 9) | 05/2022 |
| AL794.DSE.07 | Change of corporate design (pp. 1-10) | 01/2022 |
| AL794.DSE.00 | Original (pp. 1-7) | 10/2014 |

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