

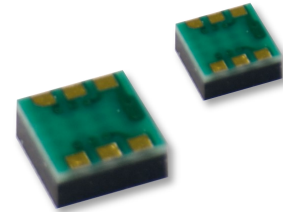
# TA903

## MagnetoResistive FreePitch Sensor

The TA903 is a position sensor based on the Tunnel MagnetoResistive (TMR) effect. The sensor contains two Wheatstone bridges with a common ground and supply pin, arranged at a relative angle of 90° to each other.

A rotating magnetic field in the sensor plane delivers two sinusoidal output signals depending on the angle  $\alpha$  between sensor and magnetic field direction. The function of these signals is  $+\sin \alpha$  and  $+\cos \alpha$ , i.e. the output signal in an end-of-shaft application has a periodicity of one per revolution.

The TA903 is available as a bare die for chip on board processing. For SMD process the TA903 is available in a LGA6B package or in a DFN8 package.



### Product Overview

| Article description       | Package      | Delivery Type |
|---------------------------|--------------|---------------|
| TA903ACA-AB <sup>1)</sup> | Die on wafer | Waferbox      |
| TA903AMA-AE               | LGA6B        | Tape and Reel |
| TA903AIA-AE               | DFN8         | Tape and Reel |
| TA903 Evalboard           | Evalboard    | ESD-Box       |

<sup>1)</sup> Minimum order quantities apply.

### Quick Overview

| Symbol     | Parameter                   | min. | typ. | max. | Unit       |
|------------|-----------------------------|------|------|------|------------|
| $V_{CC}$   | Supply voltage              | 1.8  | 5.0  | 5.5  | V          |
| $V_{Off}$  | Offset voltage per $V_{CC}$ | -3.0 | -    | +3.0 | mV/V       |
| $V_{Peak}$ | Signal voltage per $V_{CC}$ | 70   | 100  | 130  | mV/V       |
| $R_B$      | Bridge resistance           | 6.0  | 10.0 | 14.0 | k $\Omega$ |
| $R_S$      | Sensor resistance           | 3.0  | 5.0  | 7.0  | k $\Omega$ |

### Absolute Maximum Ratings

In accordance with the absolute maximum rating system (IEC60134).

| Symbol       | Parameter                                                | min. | max. | Unit |
|--------------|----------------------------------------------------------|------|------|------|
| $V_{CC}$     | Supply voltage                                           | -5.5 | 5.5  | V    |
| $H_{ext}$    | External magnetic field strength                         | -    | 180  | mT   |
| $ESB_{HBM}$  | ESD tolerance according to HBM, TA903ACA-AB              | -    | 200  | V    |
| $ESB_{HBM}$  | ESD tolerance according to HBM, TA903AMA-AE, TA903AIA-AE | -    | 2000 | V    |
| $T_{amb}$    | Operating temperature                                    | -40  | +125 | °C   |
| $T_{stg}$    | Storage temperature                                      | -40  | +125 | °C   |
| $T_{reflow}$ | Reflow temperature <sup>2)</sup>                         | -    | +250 | °C   |

<sup>2)</sup> Maximum temperature for reflow solder process.

Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device.

This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### Features

- Based on the Tunnel MagnetoResistive (TMR) effect
- Contains two Wheatstone bridges
- Sine and cosine output
- Temperature range from -40 °C to +125 °C

### Advantages

- Contactless angle and position measurement
- Large air gap
- Excellent accuracy
- Position tolerant
- Minimal offset voltage
- Minimal hysteresis

### Applications

- Incremental or absolute position measurement (linear and rotary motion)
- Motor commutation
- Rotational speed measurement
- Angle measurement (360° absolute at end of shaft)



## Magnetic Data

| Symbol           | Parameter             | Conditions | min. | typ. | max. | Unit |
|------------------|-----------------------|------------|------|------|------|------|
| B <sub>ext</sub> | Magnetic flux density |            | 30   | -    | 80   | mT   |

## Electrical Data

T<sub>amb</sub> = +25°C, V<sub>CC</sub> = 5.0 V; B<sub>ext</sub>=30mT; unless otherwise specified

| Symbol                   | Parameter                                                                                                     | Conditions                        | min.  | typ.  | max.  | Unit     |
|--------------------------|---------------------------------------------------------------------------------------------------------------|-----------------------------------|-------|-------|-------|----------|
| V <sub>CC</sub>          | Supply voltage                                                                                                |                                   | 1.8   | 5.0   | 5.5   | V        |
| V <sub>Peak</sub>        | Signal voltage per V <sub>CC</sub> <sup>1)</sup>                                                              |                                   | 70    | 100   | 130   | mV/V     |
| TC <sub>Vpeak</sub>      | Temperature coefficient of V <sub>peak</sub> <sup>2)</sup>                                                    | T <sub>amb</sub> = (-40...+125)°C | -0.25 | -0.10 | 0.00  | %/K      |
| k <sub>BareDie</sub>     | Amplitude synchronism <sup>3)</sup><br>(Version: Bare die / Sil-Gel <sup>4)</sup> )                           |                                   | 98    | 100   | 102   | %        |
| TC <sub>k(BareDie)</sub> | Temperature coefficient of k <sub>BareDie</sub> <sup>5)</sup><br>(Version: Bare die / Sil-Gel <sup>4)</sup> ) | T <sub>amb</sub> = (-40...+125)°C | -0.01 | -     | +0.01 | %/K      |
| k <sub>GlobTop</sub>     | Amplitude synchronism <sup>3)</sup><br>(Version: GlobTop <sup>6)</sup> )                                      |                                   | 97    | 100   | 103   | %        |
| TC <sub>k(GlobTop)</sub> | Temperature coefficient of k <sub>GlobTop</sub> <sup>5)</sup><br>(Version: GlobTop <sup>6)</sup> )            | T <sub>amb</sub> = (-40...+125)°C | -0.03 | -     | +0.03 | %/K      |
| V <sub>Off</sub>         | Offset voltage per V <sub>CC</sub>                                                                            |                                   | -3.0  | -     | 3.0   | mV/V     |
| TC <sub>Voff</sub>       | Temperature coefficient of differential V <sub>off</sub> <sup>7)</sup>                                        | T <sub>amb</sub> = (-40...+125)°C | -3.0  | -     | +3.0  | (μV/V)/K |
| φ                        | Phase between sine and cosine                                                                                 |                                   | 88    | 90    | 92    | deg      |
| R <sub>B</sub>           | Bridge resistance <sup>8)</sup>                                                                               |                                   | 6.0   | 10.0  | 14.0  | kΩ       |
| R <sub>S</sub>           | Sensor resistance <sup>9)</sup>                                                                               |                                   | 3.0   | 5.0   | 7.0   | kΩ       |
| TC <sub>RS</sub>         | Temperature coefficient of R <sub>S</sub> <sup>10)</sup>                                                      | T <sub>amb</sub> = (-40...+125)°C | -0.07 | -0.05 | -0.03 | %/K      |

<sup>1)</sup> Maximal signal voltage without offset influences. Periodicity of V<sub>peak</sub> is sin(α) and cos(α).

<sup>2)</sup>  $TC_{VPeak} = 100 \cdot \frac{V_{Peak}(T_2) - V_{Peak}(T_1)}{V_{Peak}(T_{RT}) \cdot (T_2 - T_1)}$  with T<sub>1</sub> = -40°C; T<sub>2</sub> = +125°C; T<sub>RT</sub> = +25°C.

<sup>3)</sup>  $k = 100 \cdot \frac{V_{Peak1}}{V_{Peak2}}$

<sup>4)</sup> Bare die on wafer-level or bare die encapsulated with Sil-Gel.

<sup>5)</sup>  $TC_k = 100 \cdot \frac{k_{T2} - k_{T1}}{k_{T_{RT}} \cdot (k_{T2} - k_{T1})}$  with T<sub>1</sub> = -40°C; T<sub>2</sub> = +125°C; T<sub>RT</sub> = +25°C.

<sup>6)</sup> Bare die mounted on PCB and encapsulated with epoxy-based dam & fill.

<sup>7)</sup>  $TC_{Voff} = 100 \cdot \frac{V_{off}(T_2) - V_{off}(T_1)}{(T_2 - T_1)}$  with T<sub>1</sub> = -40°C; T<sub>2</sub> = +125°C.

<sup>8)</sup> Bridge resistance between +V<sub>O1</sub> and -V<sub>O1</sub>, +V<sub>O2</sub> and -V<sub>O2</sub>.

<sup>9)</sup> Sensor resistance between V<sub>CC</sub> and GND.

<sup>10)</sup>  $TC_{RS} = 100 \cdot \frac{R_{S(T2)} - R_{S(T1)}}{R_{S(T_{RT})} \cdot (T_2 - T_1)}$  with T<sub>1</sub> = -40°C; T<sub>2</sub> = +125°C; T<sub>RT</sub> = +25°C.

## Accuracy

$T_{amb} = (-40...+125) ^\circ\text{C}$ ;  $B_{ext}=(30...80) \text{ mT}$ ;  $V_{CC} = 5.0 \text{ V}$ ; unless otherwise specified

| Symbol                           | Parameter        | Conditions                                                                                                        | min. | typ. | max. | Unit |
|----------------------------------|------------------|-------------------------------------------------------------------------------------------------------------------|------|------|------|------|
| $\Delta\alpha_{nom, comp} (AOP)$ | Angular error    | Amplitude, offset and phase compensation <sup>1)</sup><br>Version: Bare die or Sil-Gel encapsulated <sup>2)</sup> | -    | 0.2  | 0.6  | deg  |
| $\Delta\alpha_{nom, comp} (AOP)$ | Angular error    | Amplitude, offset and phase compensation <sup>1)</sup><br>Version: Packaged or with GlobTop <sup>3)</sup>         | -    | 0.7  | 1.4  | deg  |
| $\Delta\alpha_{nom, uncomp}$     | Angular error    | No compensation <sup>4)</sup>                                                                                     | -    | 1.0  | 2.0  | deg  |
| $\alpha_{Hys(30-50)}$            | Hysteresis error | (30...50) mT                                                                                                      | -    | 0.03 | 0.10 | deg  |
| $\alpha_{Hys(50-80)}$            | Hysteresis error | (50...80) mT                                                                                                      | -    | 0.01 | 0.03 | deg  |

<sup>1)</sup>  $\Delta\alpha_{nom, comp} (AOP) = |\alpha_{real} - \alpha_{measured}|$  with single point amplitude, offset and phase compensation due to deviations from ideal sinusoidal characteristics, incl. hysteresis error. Single point compensation := one-time compensation at room temperature (+25 °C)

<sup>2)</sup> Bare die on wafer-level or bare die encapsulated with Sil-Gel.

<sup>3)</sup> Bare die mounted on PCB and encapsulated with epoxy-based dam & fill.

<sup>4)</sup>  $\Delta\alpha_{nom, uncomp} = |\alpha_{real} - \alpha_{measured}|$  without any signal compensation, incl. Hysteresis error.

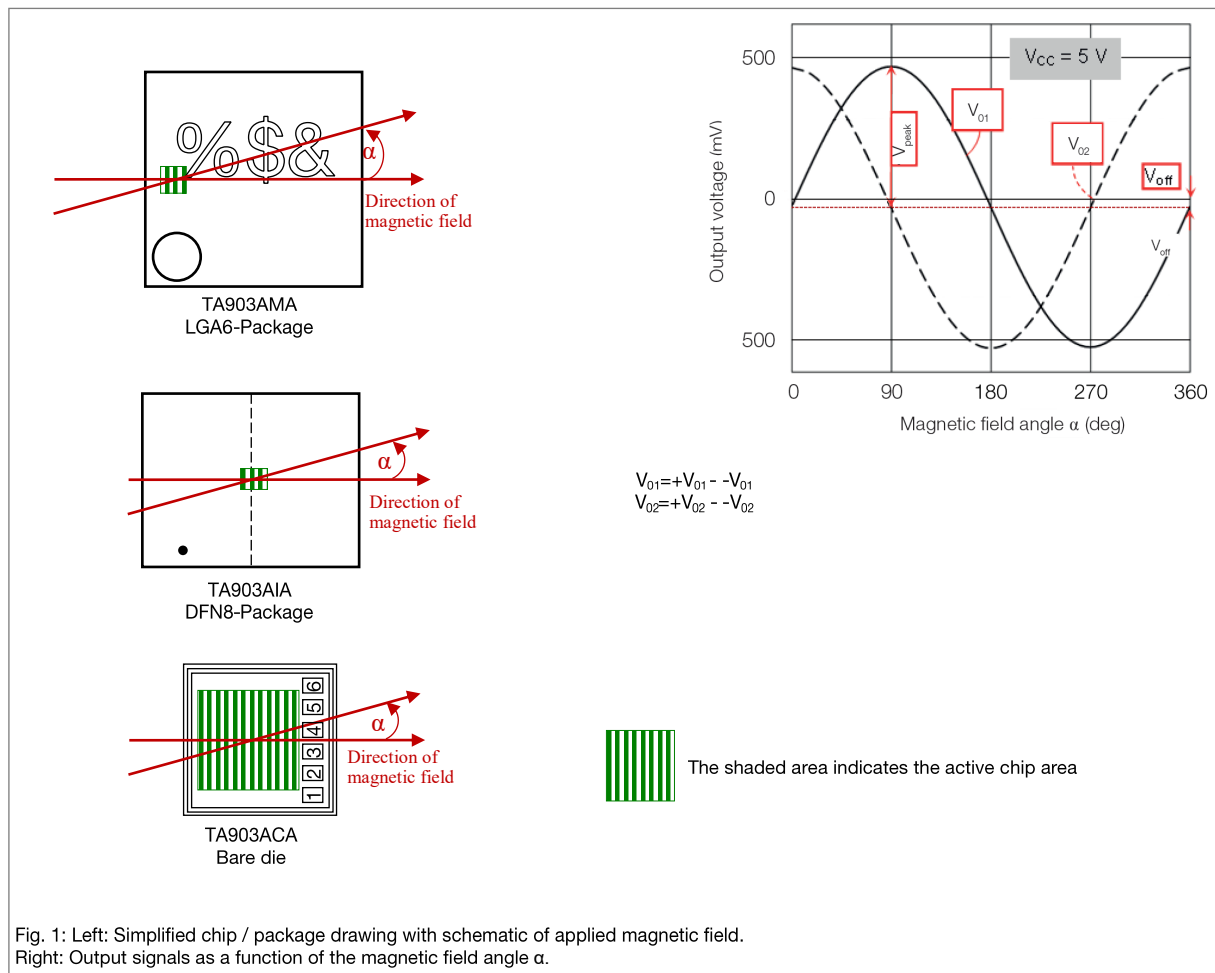
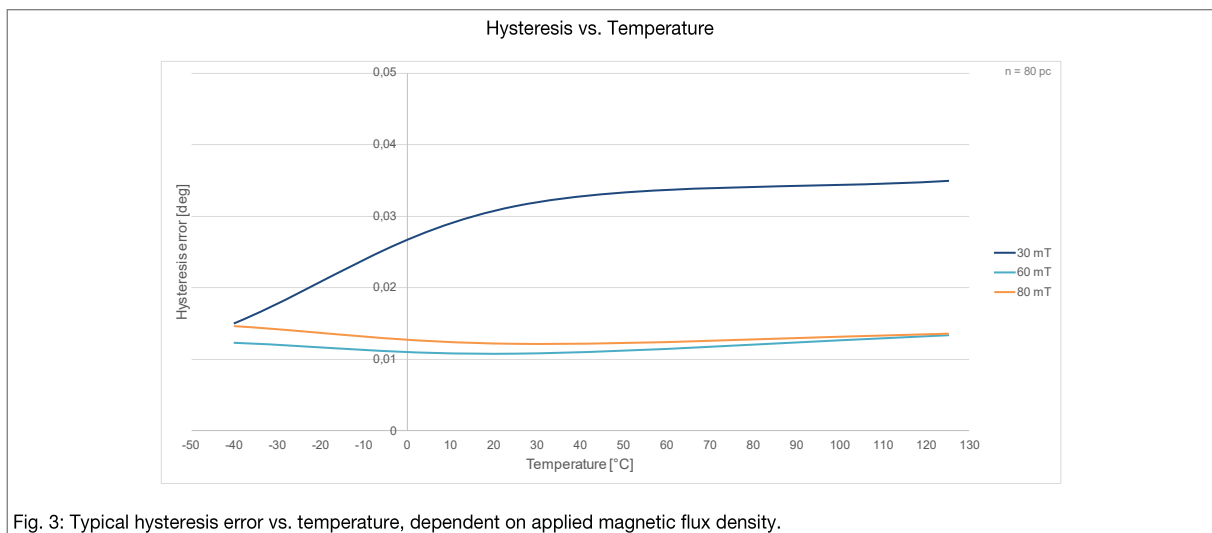
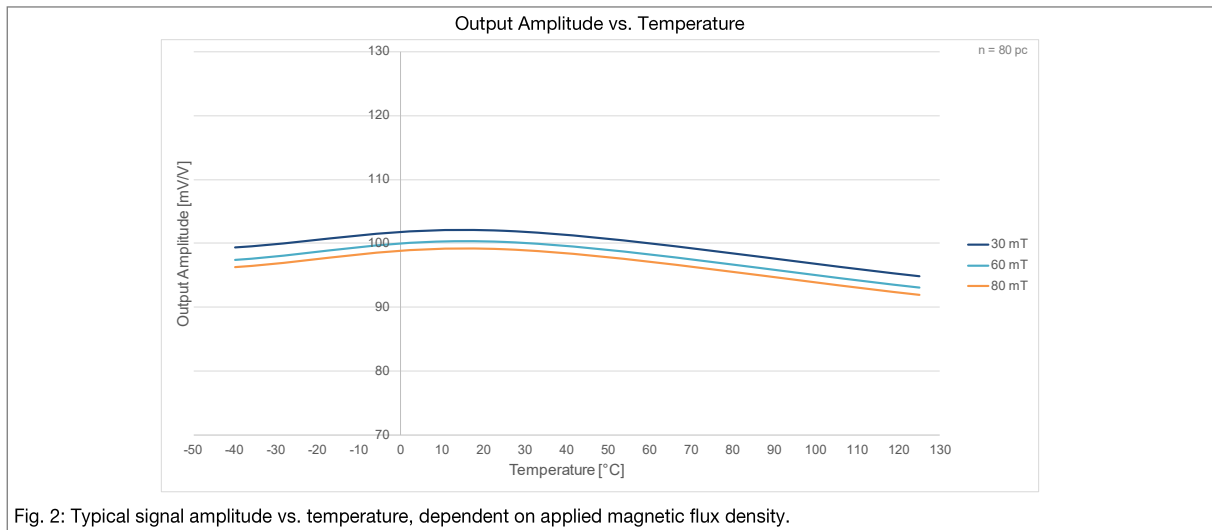


Fig. 1: Left: Simplified chip / package drawing with schematic of applied magnetic field. Right: Output signals as a function of the magnetic field angle  $\alpha$ .

## Typical Performance Graphs



## Typical Performance Graphs

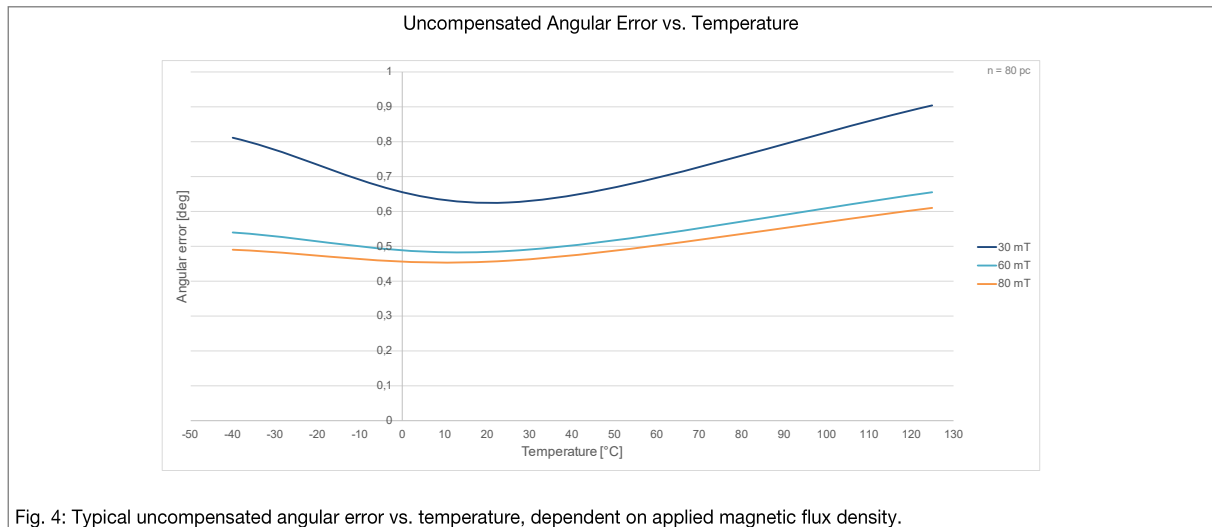


Fig. 4: Typical uncompensated angular error vs. temperature, dependent on applied magnetic flux density.

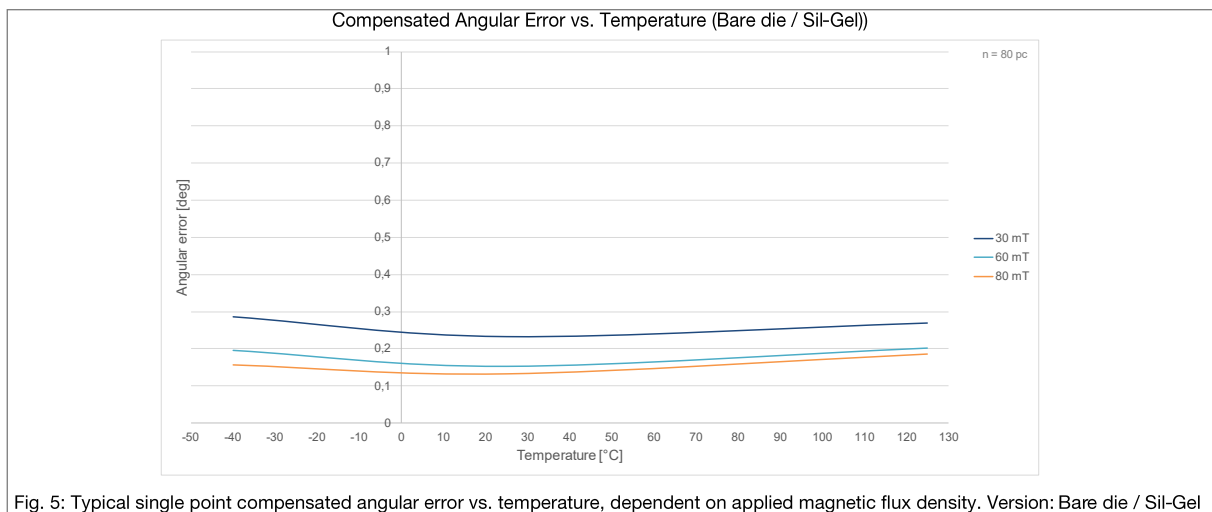


Fig. 5: Typical single point compensated angular error vs. temperature, dependent on applied magnetic flux density. Version: Bare die / Sil-Gel

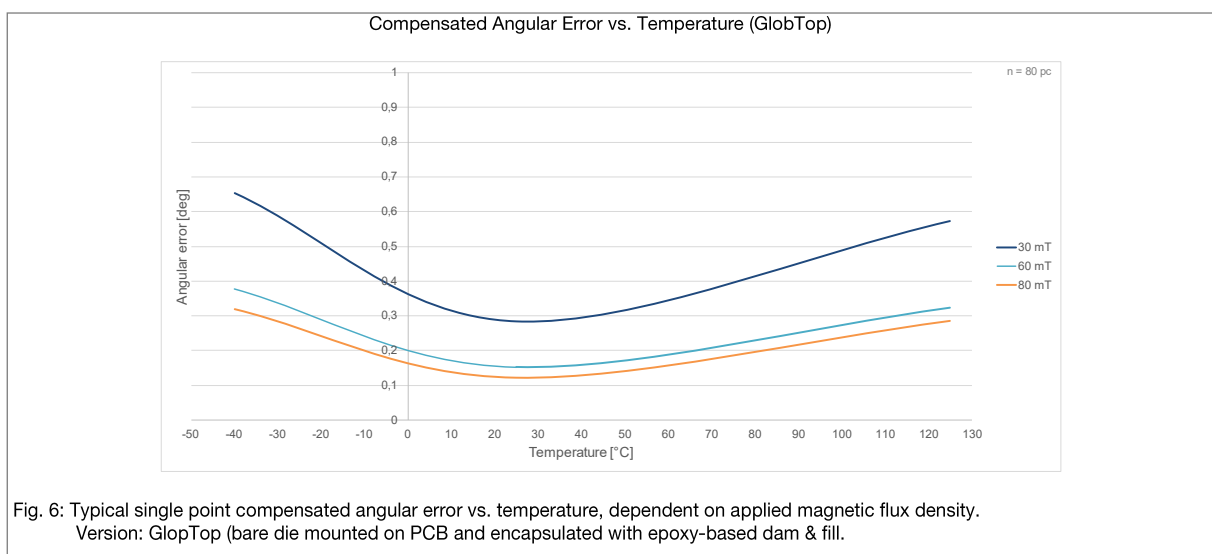


Fig. 6: Typical single point compensated angular error vs. temperature, dependent on applied magnetic flux density. Version: GlobTop (bare die mounted on PCB and encapsulated with epoxy-based dam & fill).

## TA903 Bare die

### Pinout

| Pad | Symbol    | Parameter                        |
|-----|-----------|----------------------------------|
| 1   | $-V_{O1}$ | Negative output voltage bridge 1 |
| 2   | $-V_{O2}$ | Negative output voltage bridge 2 |
| 3   | GND       | Ground                           |
| 4   | $+V_{O2}$ | Positive output voltage bridge 2 |
| 5   | $+V_{O1}$ | Positive output voltage bridge 1 |
| 6   | $V_{CC}$  | Supply voltage                   |

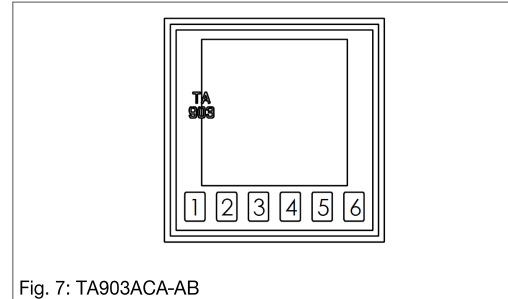


Fig. 7: TA903ACA-AB

### Dimensions

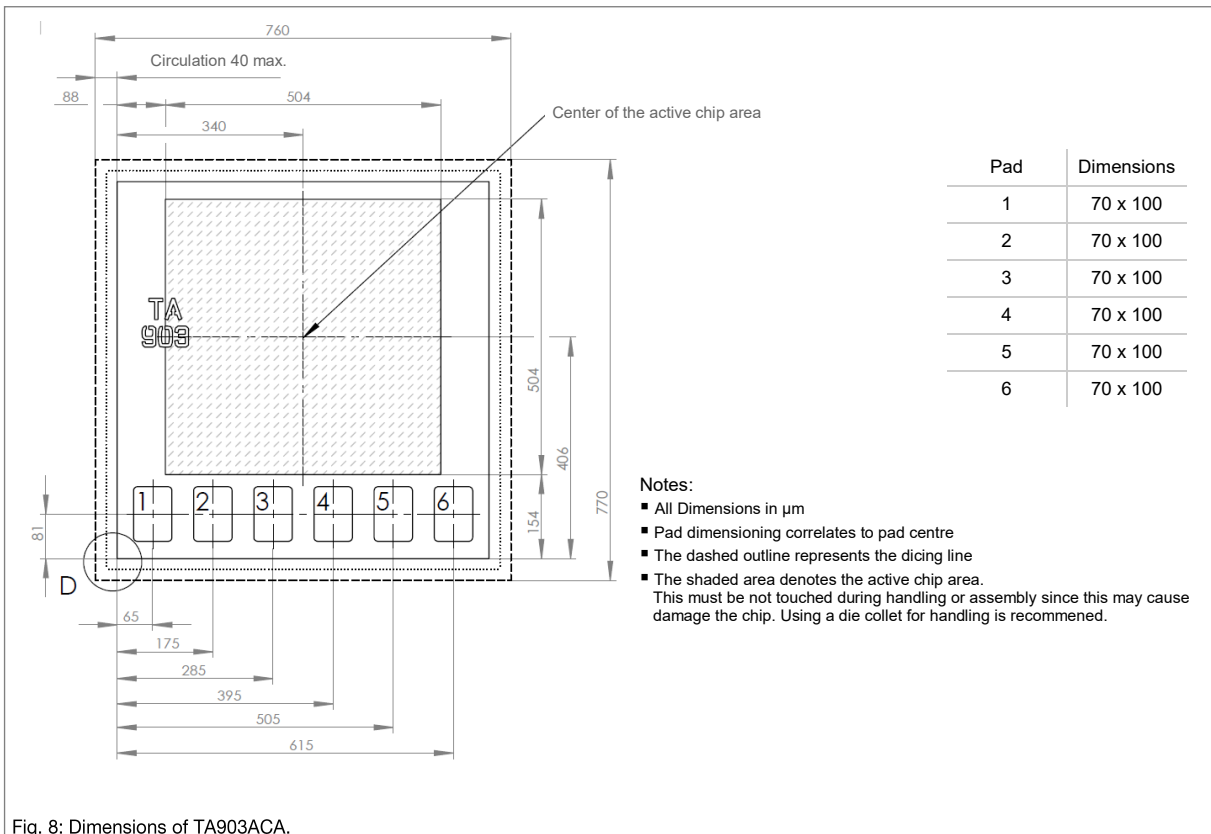


Fig. 8: Dimensions of TA903ACA.

### Data for Packaging and Interconnection Technologies

| Parameter      | Value                                  | Unit          |
|----------------|----------------------------------------|---------------|
| Chip area      | $(0.76 \pm 0.1) \times (0.77 \pm 0.1)$ | mm            |
| Chip thickness | $254 \pm 10$                           | $\mu\text{m}$ |
| Pad size       | See Fig. 8                             | $\mu\text{m}$ |
| Pad thickness  | 0.8                                    | $\mu\text{m}$ |
| Pad material   | Al                                     | -             |

## TA903 LGA6 Package

### Pinout

| Pad | Symbol    | Parameter                        |
|-----|-----------|----------------------------------|
| 1   | $-V_{O2}$ | Negative output voltage bridge 2 |
| 2   | $-V_{O1}$ | Negative output voltage bridge 1 |
| 3   | GND       | Ground                           |
| 4   | $V_{CC}$  | Supply voltage                   |
| 5   | $+V_{O1}$ | Positive output voltage bridge 1 |
| 6   | $+V_{O2}$ | Positive output voltage bridge 2 |

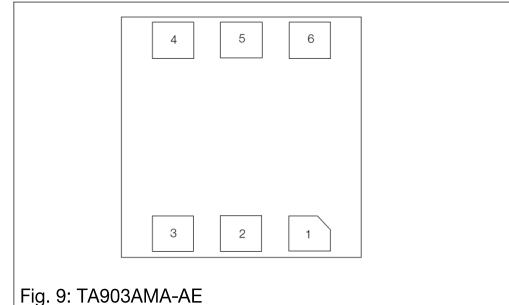


Fig. 9: TA903AMA-AE

### Dimensions

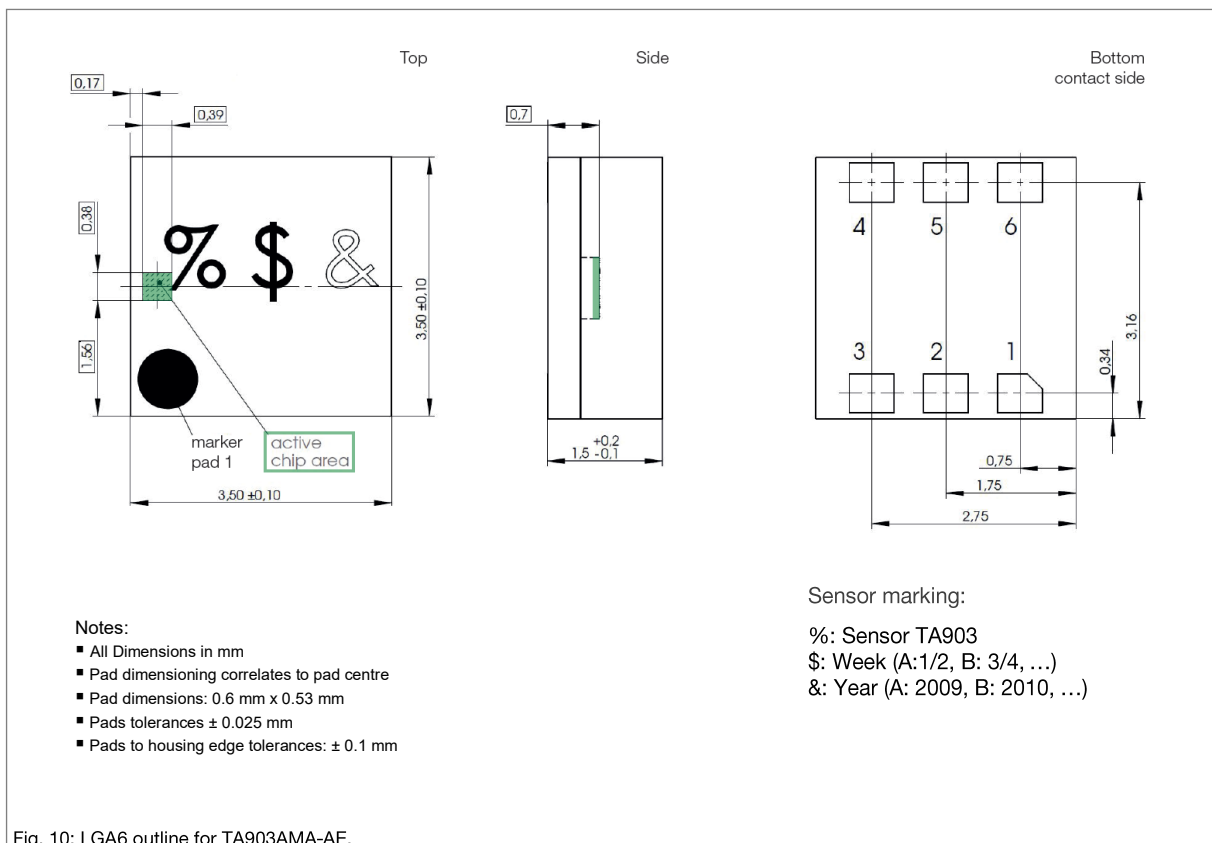


Fig. 10: LGA6 outline for TA903AMA-AE.

## TA903 DFN8 Package

### Pinout

| Pad | Symbol           | Parameter                        |
|-----|------------------|----------------------------------|
| 1   | +V <sub>O1</sub> | Positive output voltage bridge 1 |
| 2   | GND              | Ground                           |
| 3   | n.c.             | Not connected                    |
| 4   | -V <sub>O1</sub> | Negative output voltage bridge 1 |
| 5   | -V <sub>O2</sub> | Negative output voltage bridge 2 |
| 6   | +V <sub>O2</sub> | Positive output voltage bridge 2 |
| 7   | n.c.             | Not connected                    |
| 8   | V <sub>CC</sub>  | Supply voltage                   |

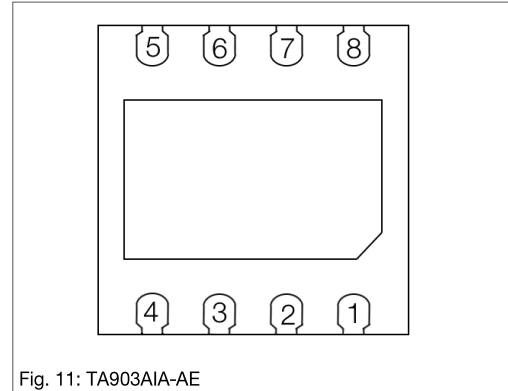


Fig. 11: TA903AIA-AE

### Dimensions

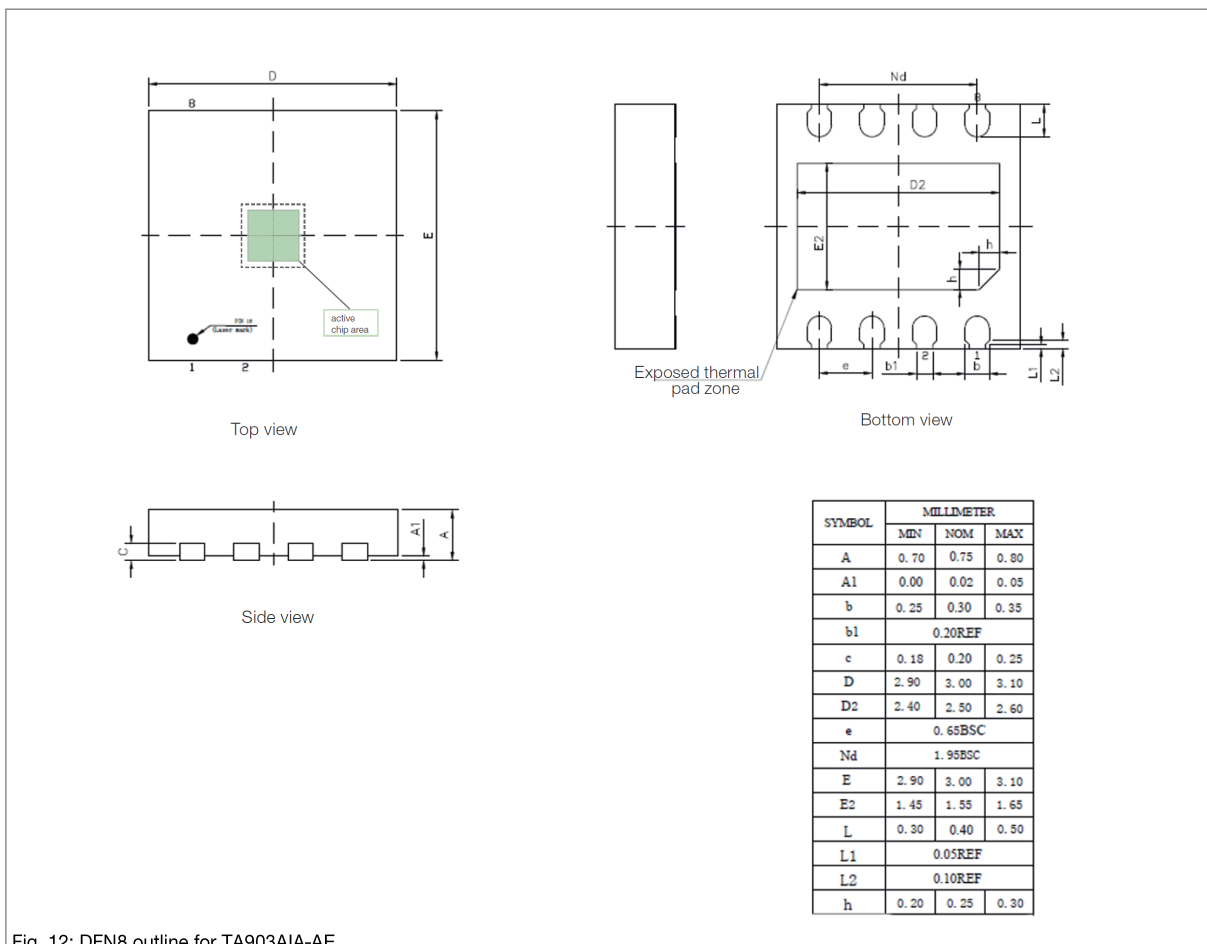


Fig. 12: DFN8 outline for TA903AIA-AE.

## Evalboard with TA903AMA-AE

### Pinout

| Pad | Symbol    | Parameter                        |
|-----|-----------|----------------------------------|
| 1   | $-V_{O2}$ | Negative output voltage bridge 2 |
| 2   | $-V_{O1}$ | Negative output voltage bridge 1 |
| 3   | GND       | Ground                           |
| 4   | $V_{CC}$  | Supply voltage                   |
| 5   | $+V_{O1}$ | Positive output voltage bridge 1 |
| 6   | $+V_{O2}$ | Positive output voltage bridge 2 |

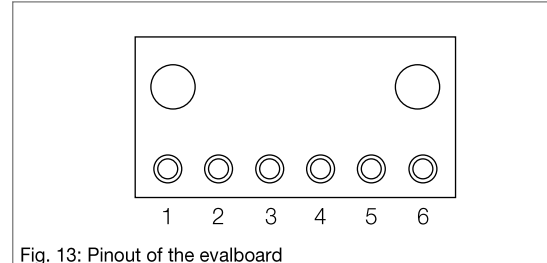


Fig. 13: Pinout of the evalboard

### Dimensions

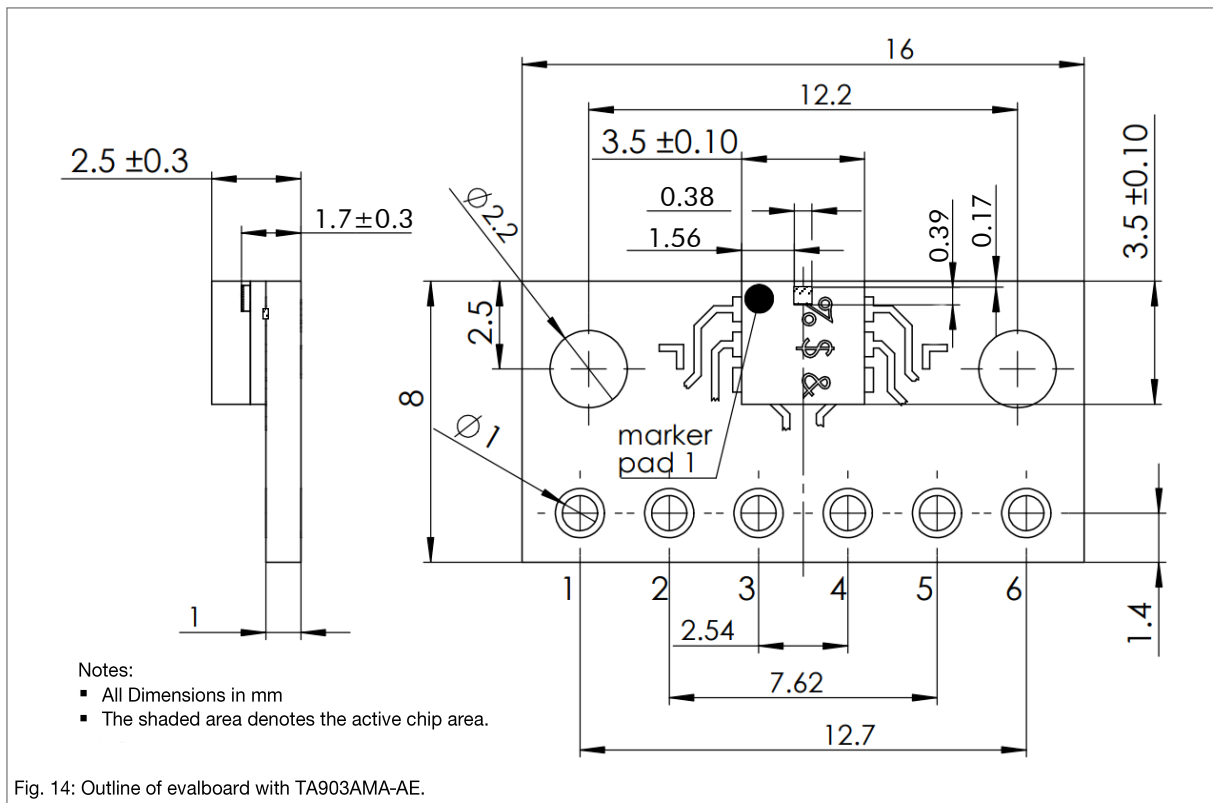
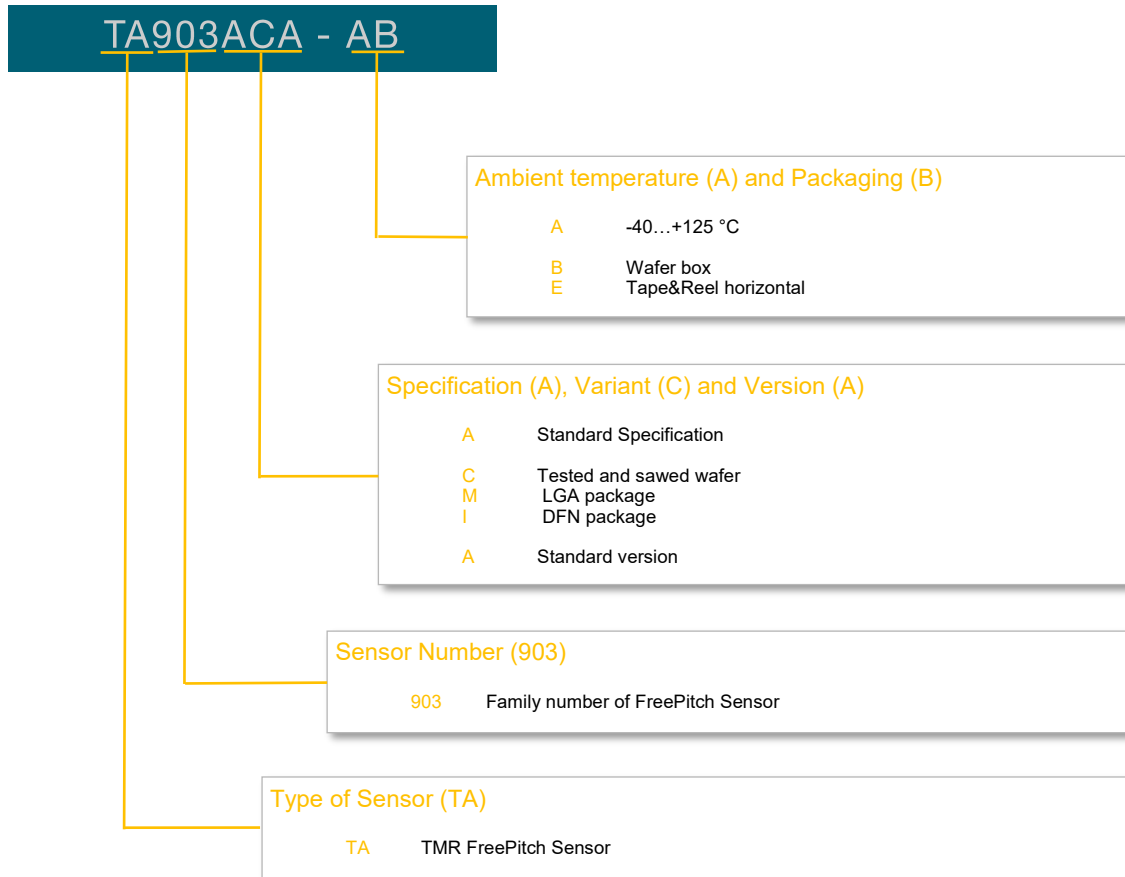


Fig. 14: Outline of evalboard with TA903AMA-AE.

### Additional Information on Ordering Code



## General Information

### Product Status

| Article         | Status                                                                                                                                                                                          |
|-----------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| TA903ACA-AB     | The product is in series production.                                                                                                                                                            |
| TA903AMA-AE     | The product is under development, qualification is on going. Deliverables have a sample status. The datasheet is preliminary.                                                                   |
| TA903AIA-AE     | The product is under development, qualification is on going. Deliverables have a sample status. The datasheet is preliminary.                                                                   |
| TA903 Evalboard | This product is for evaluation of the AL796AMA-AE sensor.                                                                                                                                       |
| <b>Note</b>     | The status of the product may have changed since this data sheet was published. The latest information is available on the internet at <a href="http://www.sensitec.com">www.sensitec.com</a> . |

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## General Information

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### Changelist

| Version      | Description of the Change                                                                | Date    |
|--------------|------------------------------------------------------------------------------------------|---------|
| TA903.DSE.10 | Correction of wrong pinning (p. 6)                                                       | 10/2025 |
| TA903.DSE.09 | Add evalboard information (p. 9)                                                         | 12/2024 |
| TA903.DSE.08 | Fix of incorrect y-axis labelling in Fig. 1 (p. 3), Change of corporate design (pp. 1-9) | 05/2024 |
| TA903.DSE.07 | Disclaimer supplement                                                                    | 06/2022 |
| TA903.DSE.06 | Install Chipposition in the DFN8 drawing (p. 8)                                          | 03/2022 |
| TA903.DSE.05 | Change of corporate design (pp. 1-10)                                                    | 01/2022 |
| TA903.DSE.00 | Original (pp. 1-7)                                                                       | 11/2016 |

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